Time

Optimal Solution

Computation Time

Nonholonomic constraint - fuel used to drive a car from point A to point B on a 2D plane

Rate of convergence – time because of the number of iterations

High memory requirements

Path cost

Rate of exploration

Execution Time

Biasing Radius – radius of a sphere

Number of Nodes

Tree Density Plot - number of nodes per area

Run-Time overhead - the extra time it takes for a program to run